





#### **UNISEC-EGYPT:**

## **Space Education and Research**

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## **Outline**

- UNISEC-EGYPT and Space Systems Technology
  Laboratory (SSTLab) previous activities.
- The Egyptian space Agency.
- UNISEC-EGYPT 2017 Training activities.
- UNISEC-EGYPT 2017 Research activities.
- Future Plan.

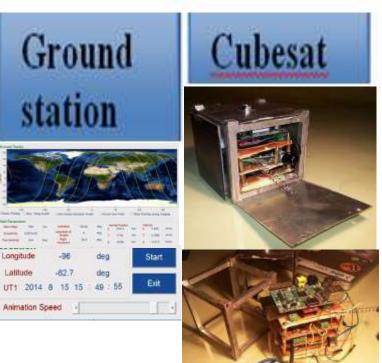


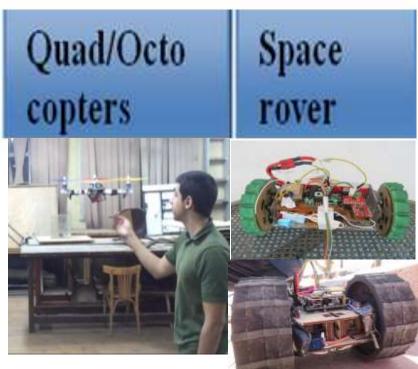




- SSTLab (2011) is the host of All Unisec-Egypt activities in Cairo
- We have been working on:







## Egypt Approves Establishing Egyptian Space Agency

- There was a governmental debate about the need for a space agency since 2015.
- The Council of Ministers has approved on Wednesday (SEPTEMBER 27, 2017) establishing a space agency aimed at space scientific research following years of preparation.
- The new law has been referred to the parliament for final agreement in hopes to expose Egypt to the world community of space technology.
- Aerospace Department, Cairo University will be the main source for Engineers and researchers in the new agency (We have to prepare for that).

# UNISEC-EGYPT 2017 Training Activities

Professors Training.

CanSat Training Program (CTP7).

Rover Training Program (RTP1).

Seminars.

## **Professors Training**

We have two "Space" active professors in AE department

Prof. Ayman Kassem



Prof. Mohamed Khalil



CLTP8 (Hepta-sat) 9/2017



One year at Nihon University

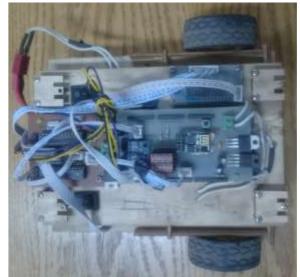
#### **CanSat Training (CTP7)**

- The content taught to trainees have been improved.
- Starting from the basic concepts about satellites to design, fabricate, test and launch a fully designed

module of CanSat.



## **Rover Training Program (RTP1)**







#### **Seminars**

Introduction to satellites.



#### **Seminars**

Introduction to Hepta-Sat.





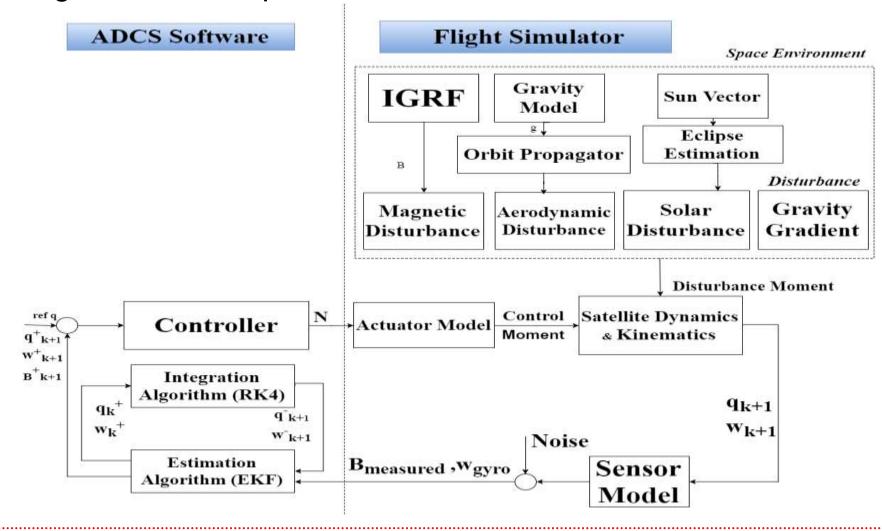
## UNISEC-EGYPT 2017 Research Activities

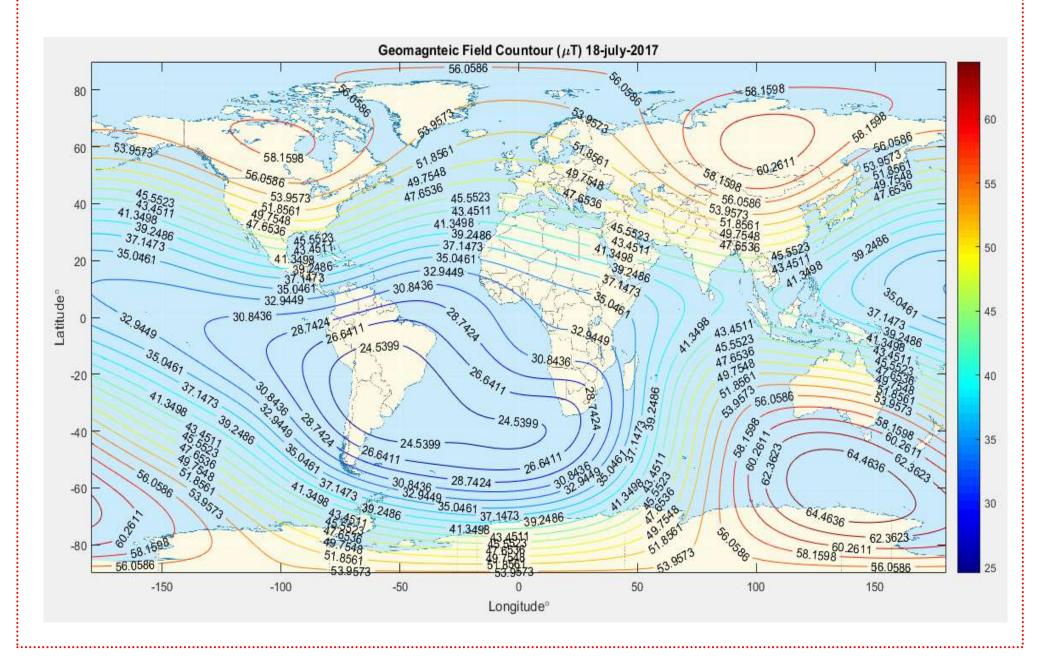
Graduation Projects.

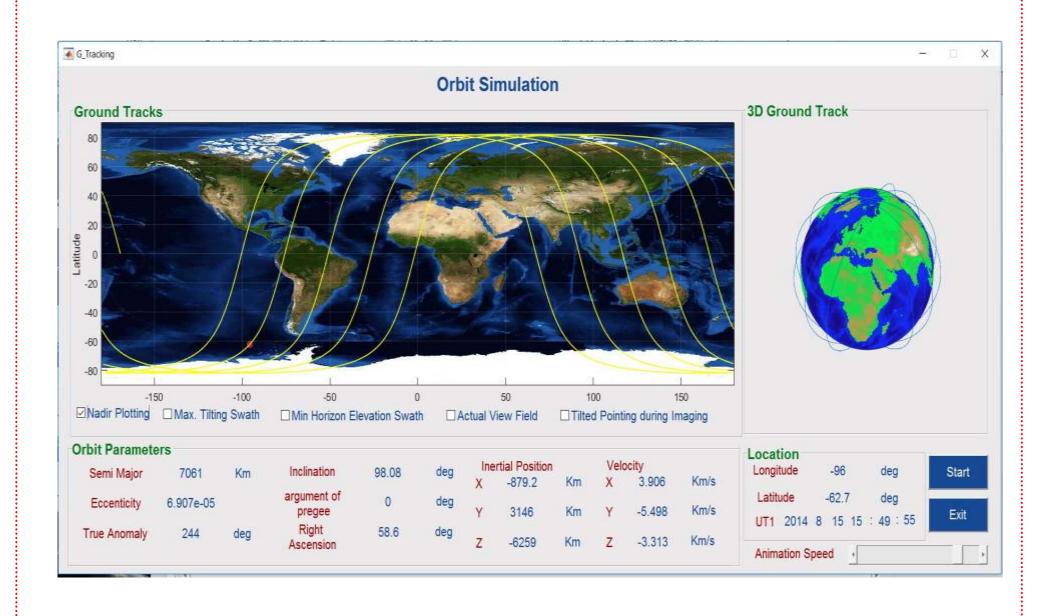
Master Theses.

## **Graduation Projects**

1- Design ,Test and Implementation of the ADCS software

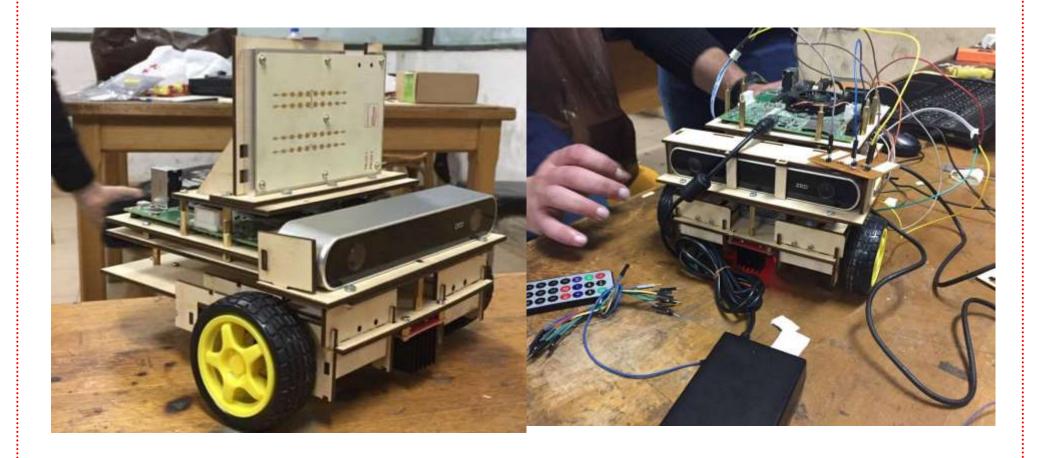


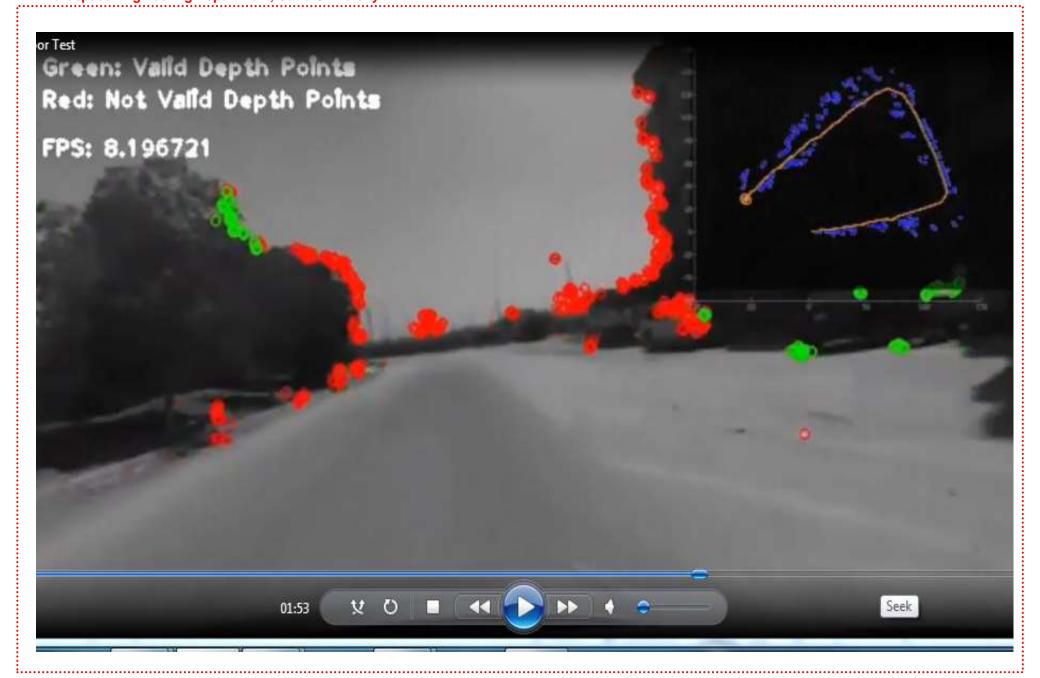




## **Graduation Projects**

2- simultaneous localization and mapping (SLAM)

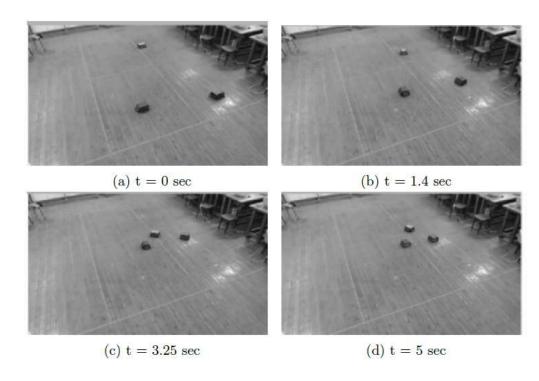




#### **Master Theses**

• Finished Master thesis: ROVER NETWORKS USING DISTRIBUTED CONTROL TECHNIQUES (Formation)





Work in progress: SLAM, Object recognition, High fidelity orbit propagators.

### **Future Plan**

- Continue with our educational and research programs and improve it.
- Cooperation with Unisec-global and Nihon University to have a Heptasat training in Egypt.
- Set the Can-sat program to pre-college and start our first Hepta-sat education program for AE students.
- Concentrate on space research to graduate enough engineers for the

Egyptian Space Agency.



## Ready for Questions