

UNISEC ROME, DECEMBER 2017



Introduction

Hyperion Technologies B.V.

Founded August 2013

Started activities in 2011

Design and manufacturing

of products for small satellites



Main activities

Development of subsystems and components for small satellites

- Customer specific development of hardware and software, mainly for small satellites and other high-tech applications
- Consulting on small satellites and missions



Vision

- ✤ Develop high-performance, best-in-class systems for small satellites
- Use of COTS components when available and possible
- Extensive testing
 - Thermal vacuum
 - Vibration
 - Radiation
- ✦ High Performance and High Reliability
 - Robust
 - Failure tolerant
 - Similar to professional systems



Product overview

Products developed by Hyperion Technologies

Various versions of products (options)

Customer specific developments

Future products



ST200

World's smallest star tracker

Stand alone device

< 30 arcseconds resolution (3-sigma)

Magnitude 6 stars

600 mW average power consumption

5 Hz update rate

Standard and custom baffles available







Hyperion's reaction wheels

The reaction wheels allow for control the attitude of the satellite

HT-RW210: optimized for 1-3U cubesats

+ Dimensions: 25x25x15 mm³

HT-RW400: Optimized for 6-12U cubesats

+ Dimensions: 50x50x27.5 mm³





Magnetorquers

HT-MTQ200 Series

- 80x11x11 / 25x19x19 mm³
- Intended for small (up 4U) CubeSats
- Highly efficient
- Two models:
 - HT-MTQ200.20: 0.2 \mbox{Am}^2 , 100 mW, boost to 1 \mbox{Am}^2
 - HT-MTQ200.15: 0.15 Am², 300 mW, boost to 0.25 Am²

HT-MTQ400 Series

- 80x12x12 / 65x16x16 mm³
- Intended for 6-12U CubeSats
- Highly efficient
- Two models:
 - HT-MTQ400.40: 0.4 Am², 300 mW, boost to 2 Am²
 - HT-MTQ400.50: 0.5 Am², 500 mW, boost to 1.5 Am²

Drive electronics can be tailored to application.





Hyperion's iADCS

The integrated ADCS determines and controls the attitude of the satellite

HT-iADCS100: intended for 1-3U cubesats

+ Dimensions: 90x96x32 mm³

HT-iADCS400: intended for 6-12 U cubesats

+ Dimensions: 96x96x66 mm³





iADCS-100

1/4 unit CubeSat compatible

Pointing knowledge < 30 arcseconds

Pointing accuracy << 1 degree

< 1.8 W power consumption (< 3W peak power)

Fully autonomous modes:

- Target tracking
- Sun pointing
- De-tumbling
- Nadir pointing
- 3 axes stabilization for up to 3U CubeSats
 - Reaction wheels
 - Magnetorquers





iADCS-400

0.7 unit, CubeSat compatible

Pointing knowledge < 30 arcseconds

Pointing accuracy << 1 degree

< 6 W power consumption (peak power)

Fully autonomous modes:

- Target tracking
- Sun pointing
- De-tumbling
- Nadir pointing
- 3 axes stabilization for 6-12U CubeSats
 - Reaction wheels (30 mNms, up to 2 mNm torque. 60 mNms is optional)
 - Magnetorquers (0.5 Am2)





iACS-200

1/4 unit CubeSat compatible

Pointing knowledge: depending on sun-sensors and magnetometers

Pointing accuracy < 3 degrees

- < 1.2 W power consumption (< 3W peak power)
- 3 axes stabilization for up to 3U CubeSats
 - Reaction wheels
 - Magnetorquers
 - External sun-sensors
 - Internal IMU
 - Optional control software





Hyperion's propulsion systems

Increasing mission life time from days to years

- PM400 Propulsion unit
- Dimension: 2U
- Thrust: 1N
- Bipropellant
- 3D printed
- Safe and non-toxic

- Your satellite where it has to be
- Orbit maintenance
- Orbit control
- De-orbiting





Hyperion's imager The imager is based on star tracker heritage

HT-IM.200.16: currently available for CubeSats

- Dimensions: 30x32x38 mm³
- 5 Hz image rate
- 4 Mpixel resolution
- Fast USB-interface available
- Monochrome or color version available





Hyperion's payload processor

The payload processor allows for high performance flexible computing with a small footprint

CP400.85: currently available

Dimensions: 50x20x5 mm³

- •500 MHz
- •512 MB Ram
- Plug and play ready design
- Linux based operating system
- "Desktop computer in a satellite"





Contact information



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