

## 7<sup>th</sup> Nano-Satellite Symposium

# ASELSAT: High Resolution High Speed CubeSat

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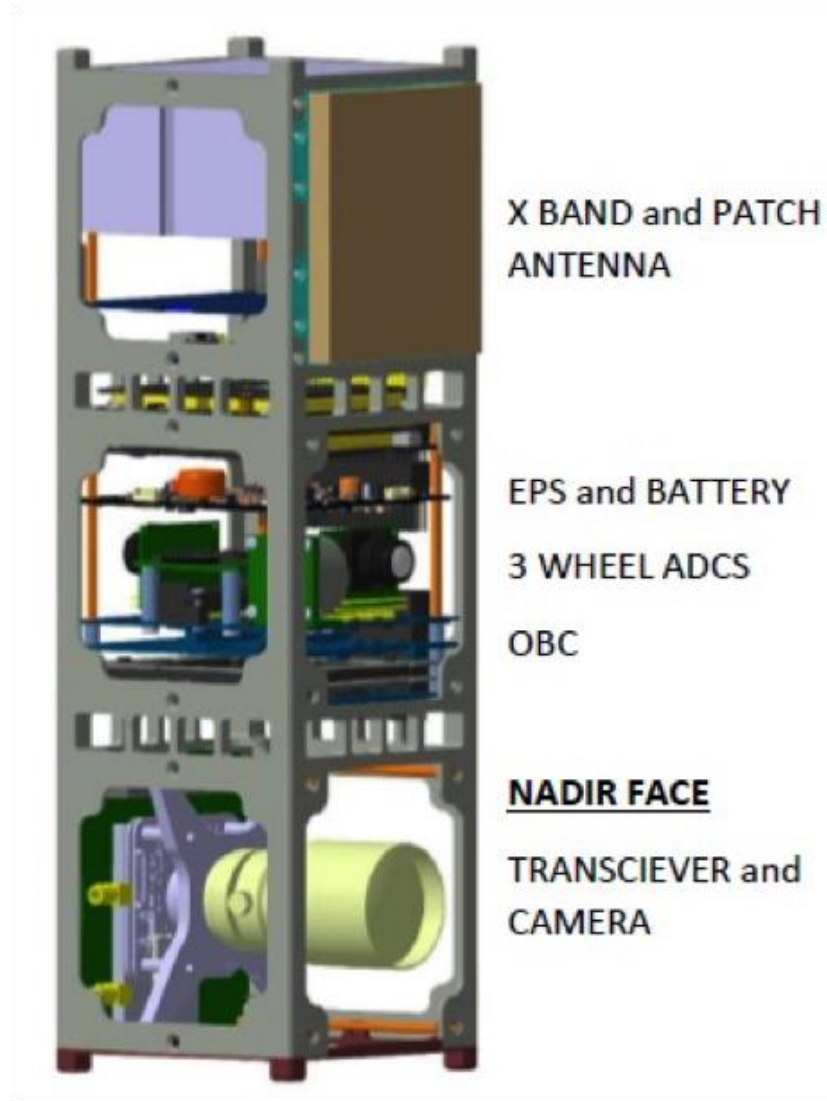


# Overview

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- 3u CubeSat at 500km SSO
- Main payload is miniaturized X-Band Transmitter
- Taking pictures 30m GSD
- Secondary payload is a dosimeter

# General Design



- The main mission of the satellite is to take images and transmit it to a ground station via X-Band Transmitter. For this purpose, the design is focused on
  - Command and data handling
  - Attitude control and pointing accuracy
  - Power generation

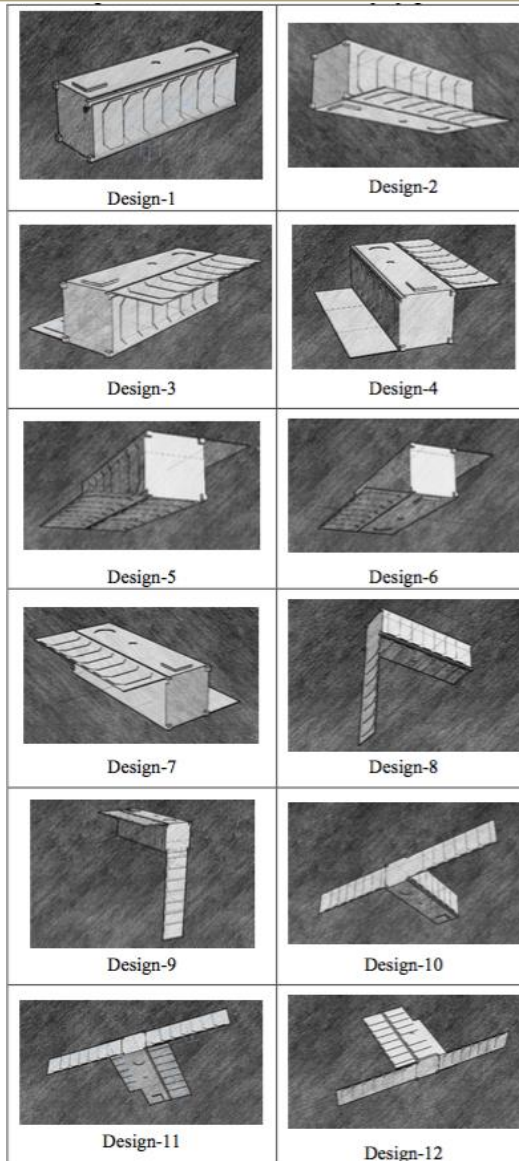


# Power Budget

		Assumptions	
Altitude		500 km SSO	
Albedo		10%	
Orbit Period		5686 sec	
Inclination		97.4 Degree	
		<i>Normal Mode Orbit Average</i>	
	Power Req. (W)	Duty Cycle (%)	Power Consumed (W)
Camera	3	10	0.3
ADCS (Torquers at max)	2.236	100	2.236
X-Band	20	2	0.4
OBC	0.1	100	0.1
Modem	4	10	0.4
Beacon	1.5	16.7	0.2505
EPS	0.1	100	0.1
<b>Total Power Consumed</b>			<b>3.7865</b>
<b>Average power generated per orbit</b>			<b>5.94</b>
<b>Margin (%)</b>			<b>36.25420875</b>



# Solar Panel Configuration Analysis

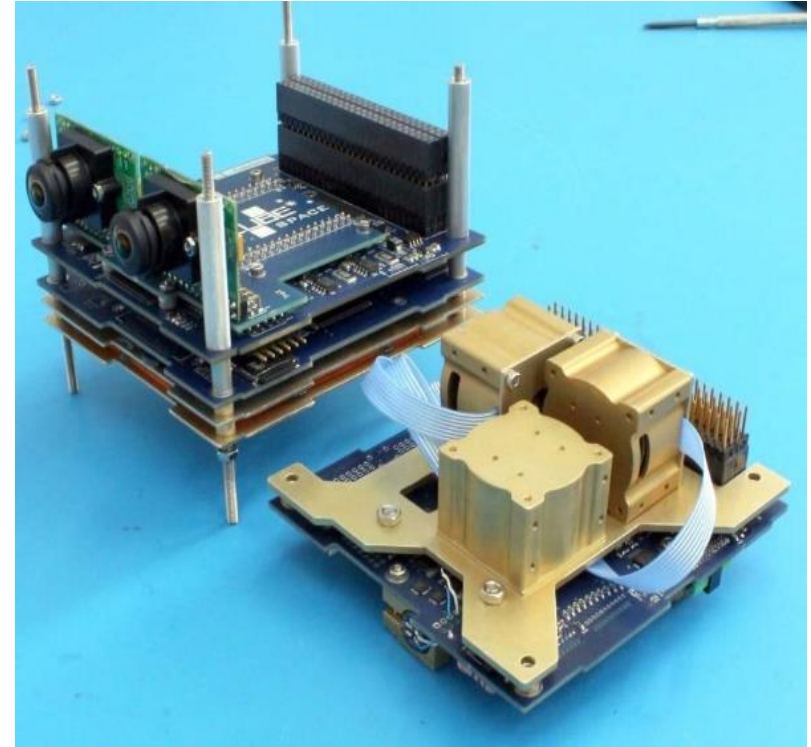
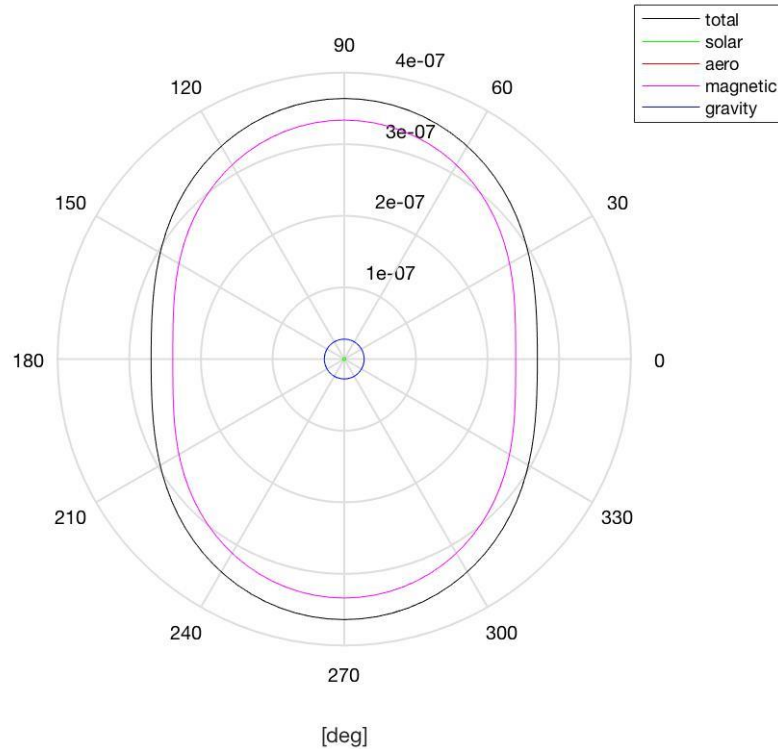


	12AM-12PM (Watt)	6 AM-6 PM (Watt)	9 AM-9 PM (Watt)
<b>Design-1</b>	2.99	8.91	6
<b>Design-2</b>	3.2	9.64	6.3
<b>Design-3</b>	3.27	10.09	4.9
<b>Design-4</b>	5.77	10.09	6.24
<b>Design-5</b>	5.77	10.09	6.24
<b>Design-6</b>	3.15	2.27	2.58
<b>Design-7</b>	5.76	10.1	6.57
<b>Design-8</b>	4.10	9.63	7.44
<b>Design-9</b>	4.31	<b>10.36</b>	7.75
<b>Design-10</b>	6.68	9.96	<b>8.42</b>
<b>Design-11</b>	6.78	3.59	5.53
<b>Design-12</b>	<b>9.39</b>	3.61	7.31

- Calculation total disturbance torques
  - Atmospheric
  - Gravity gradient
  - Magnetic
- Momentum Wheel sizing
  - 80% Cyclic Angular Momentum
  - 20% Secular Angular Momentum







Total Angular Momentum	1.8 mNms
Cyclic Angular Momentum	1.4 mNms
Secular Angular Momentum	0.36198 mNms

Small CubeWheel	
Maximum momentum storage	1.7 mNms
Maximum wheel speed	± 8000 rpm
Maximum torque	0.15 mNm

# TMTC and Ground Station

- X-Band
- UHF-VHF
- Ax.25 Protocol
- Software for commanding satellite is being developed.



# Conclusion and Future Work



- Project is in the PDR phase.
- Challenges with subsystems
- Expected to be completed 2018



# Thank You!

