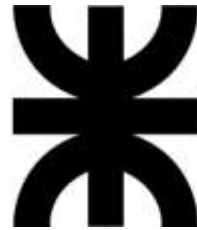


# Sail deployment deorbit system by solenoids for microsattellites



Club de Robótica



Universidad Tecnológica  
Nacional  
Facultad Regional  
Córdoba



Argentina



“A group of students that shares a common interest related to robotics and open-source applications and now embarking In the aerospace field”



UTN-FRC





# The team

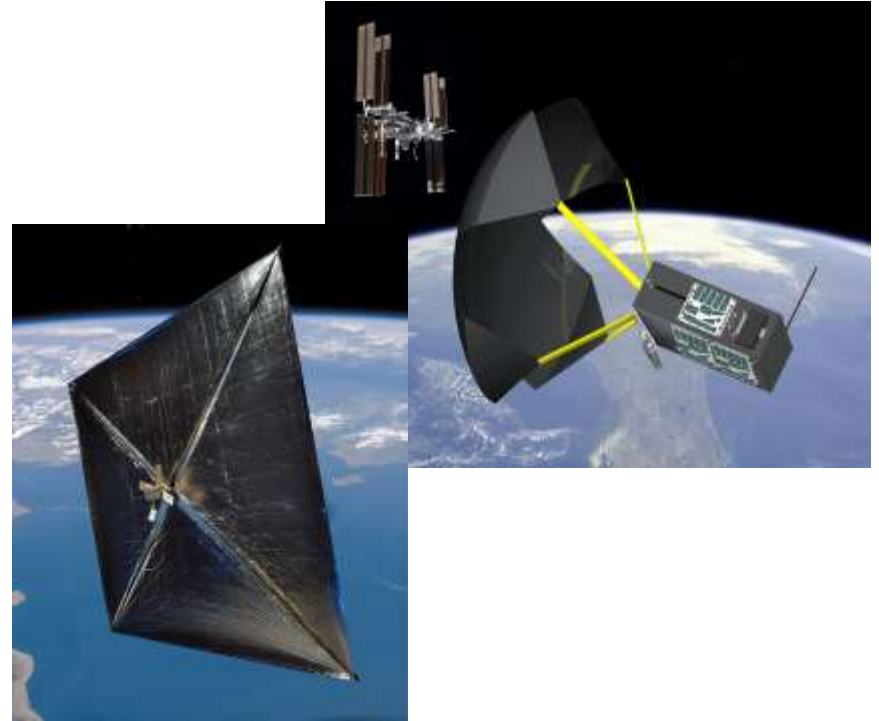


Sail deployment deorbit system by solenoids for  
microsatellites



# The beginnings

- **Atmospheric drag** is the major cause of orbital decay for LEO satellites.
- Sail deployment is a known way to augment the drag area.



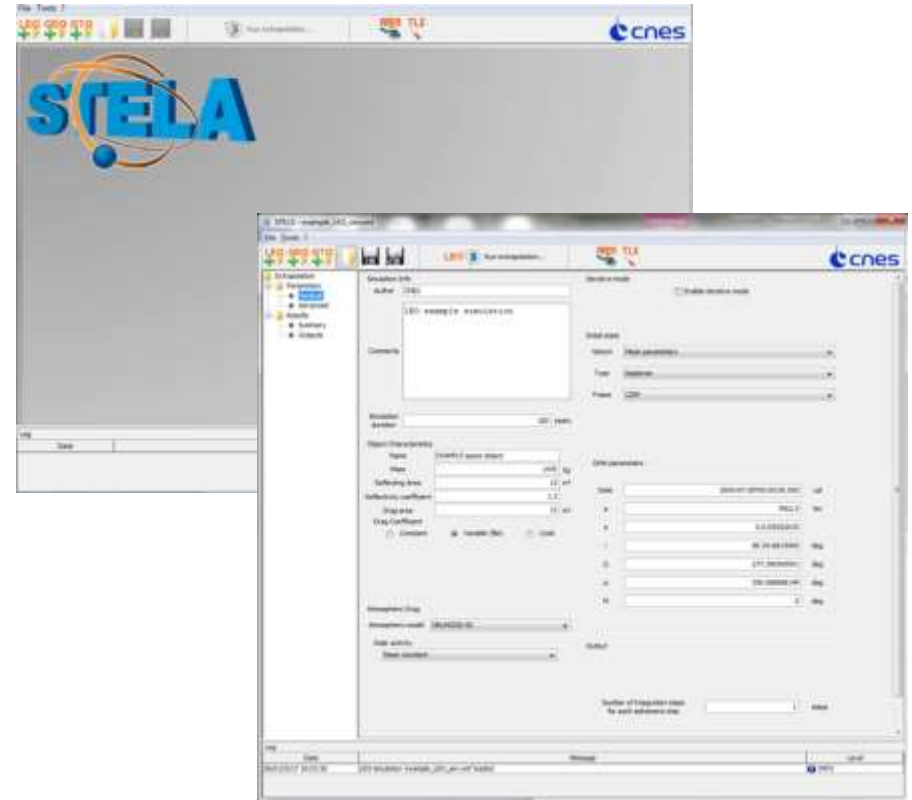
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# Simulations

Analytic simulation tool used to propagate orbit:

- STELA v3.1.1 by CNES



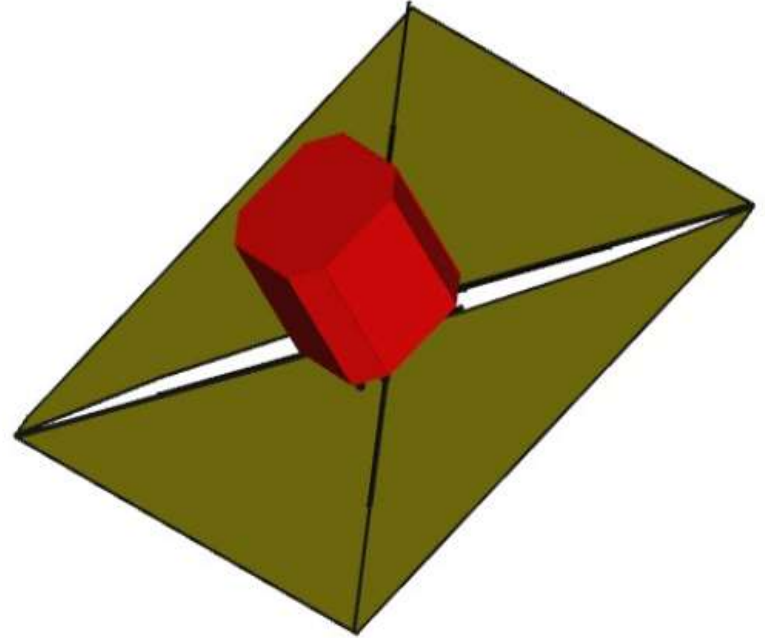
# Proposed deorbit device

Our objectives:

- Scalable
- Easy construction

Description:

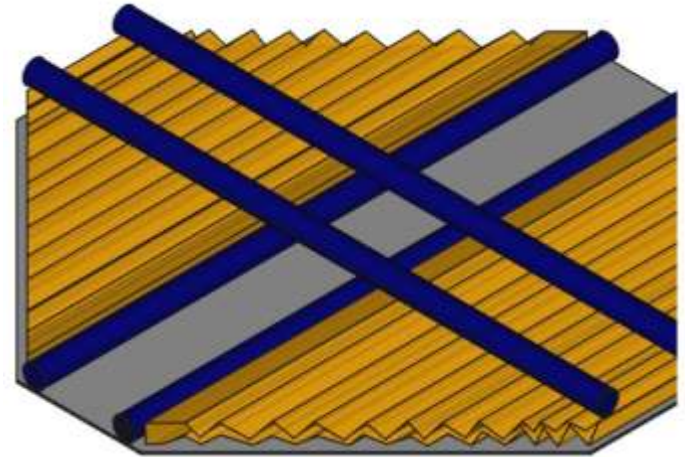
- Telescopic arms
- Move by linear motors
- Fail-safe construction
  - A bad deploy still augment the area drag area



# Deployment Mechanism

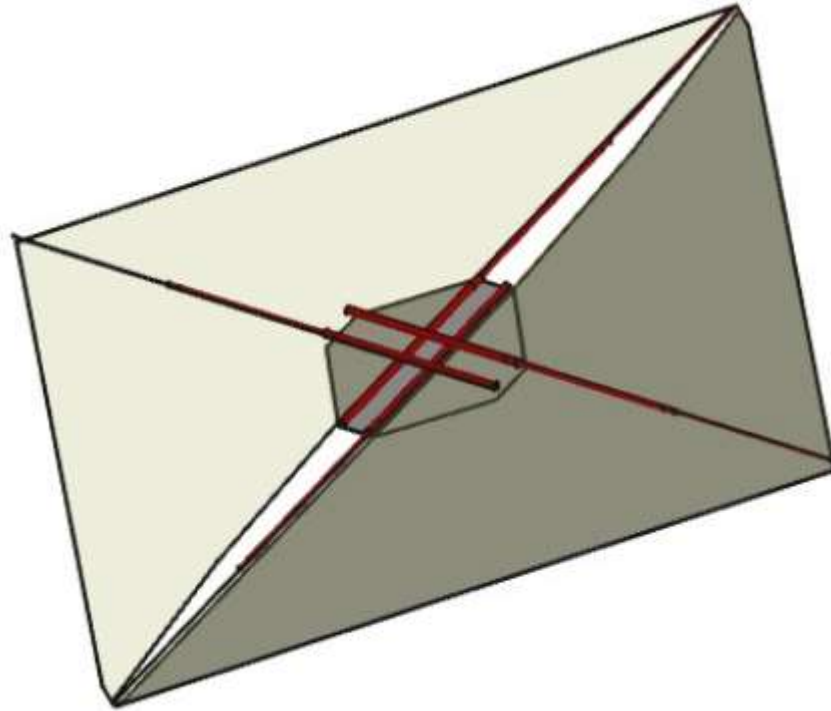
Principles:

- Telescopic arms.
- Interaction between the solenoid and magnets.
- Linear Motor.





# Telescopic arm



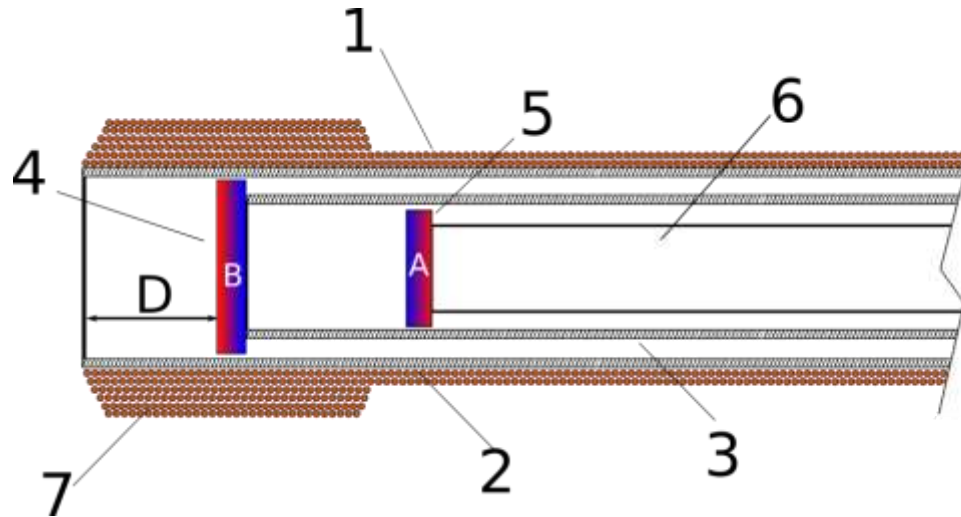
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# Solenoid

Three hollow cylinders with a copper winding to deploy a sail.

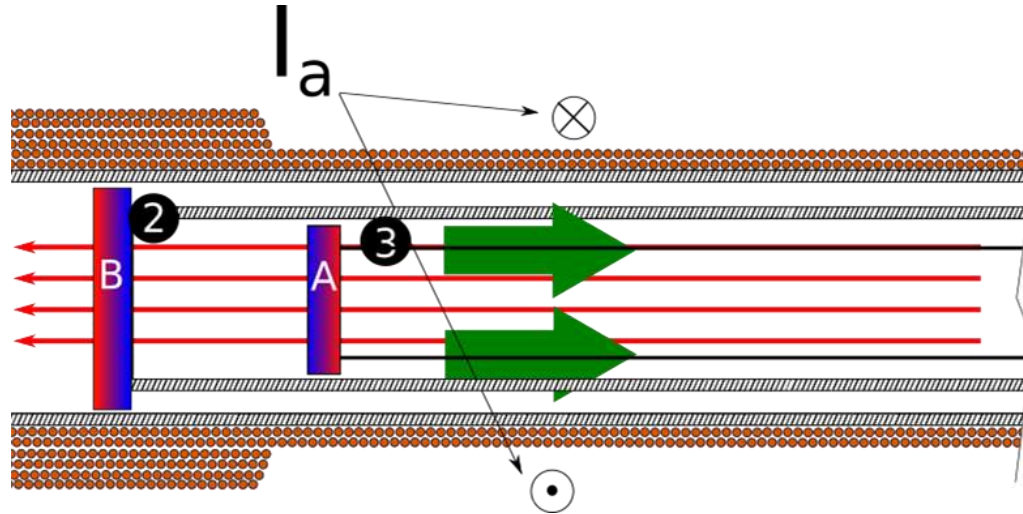


- 1) Copperwire.
- 2) Extern cylinder.
- 3) Inner cylinder one.
- 4) Magnet B.
- 5) Magnet A.
- 6) Inner cylinder two.
- 7) Aux. copperwire.



# Telescopic Arms

Three hollow cylinders with a copper winding to deploy a sail.

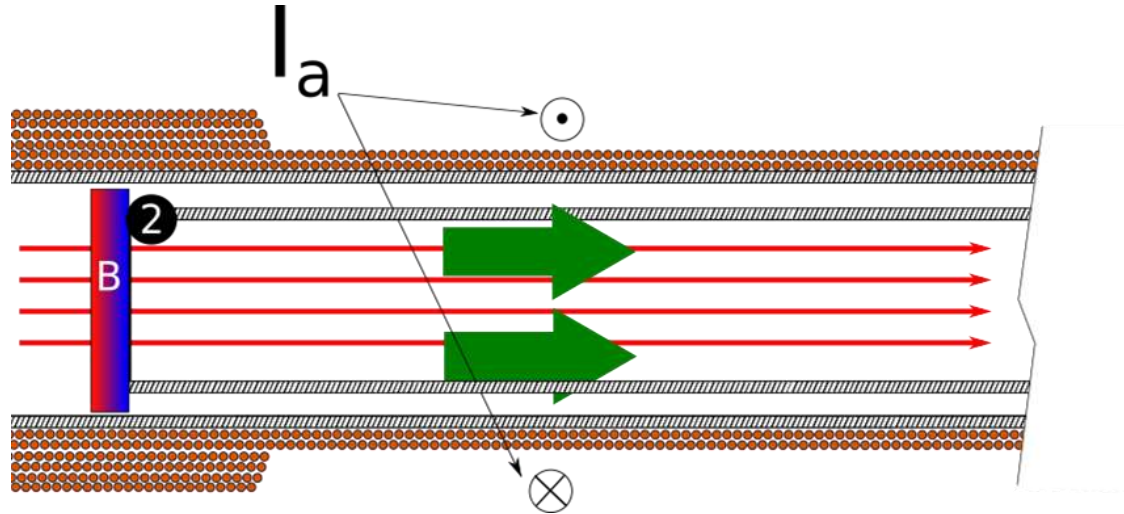


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# Telescopic Arms

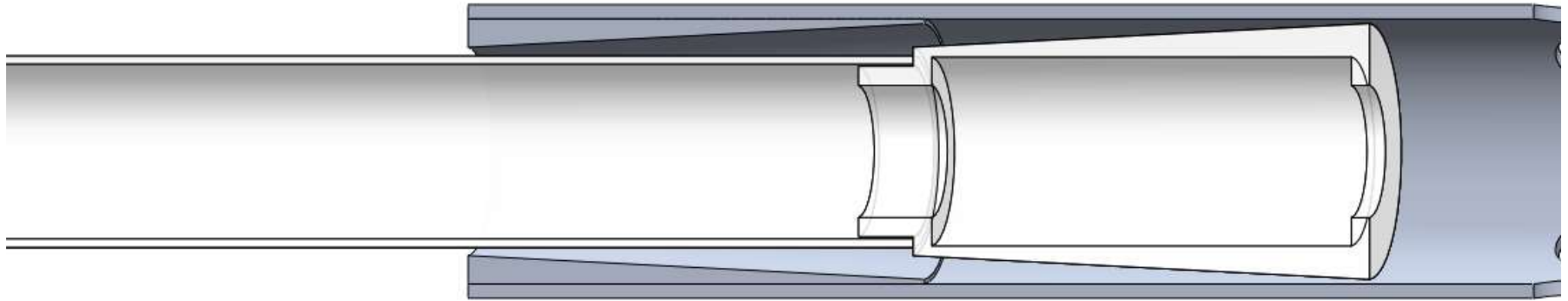
Three hollow cylinders with a copper winding to deploy a sail.



Sail deployment deorbit system by solenoids for  
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# Deploy - Mechanical Stop



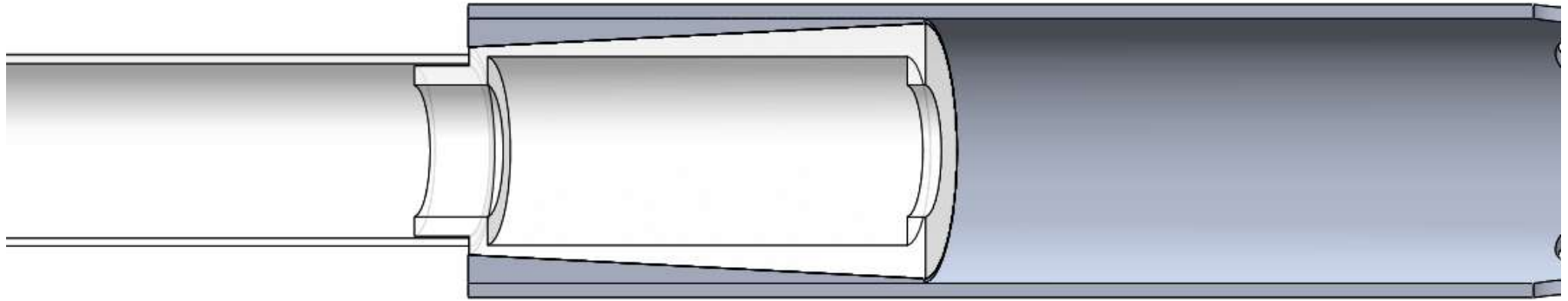
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# Deploy - Mechanical Stop

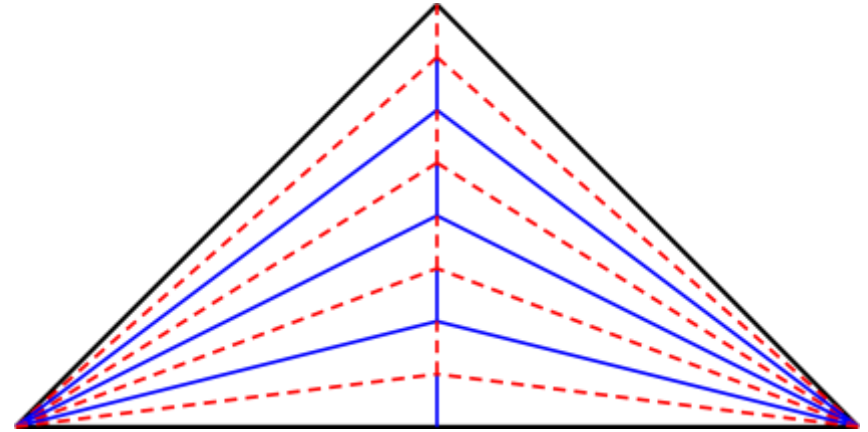
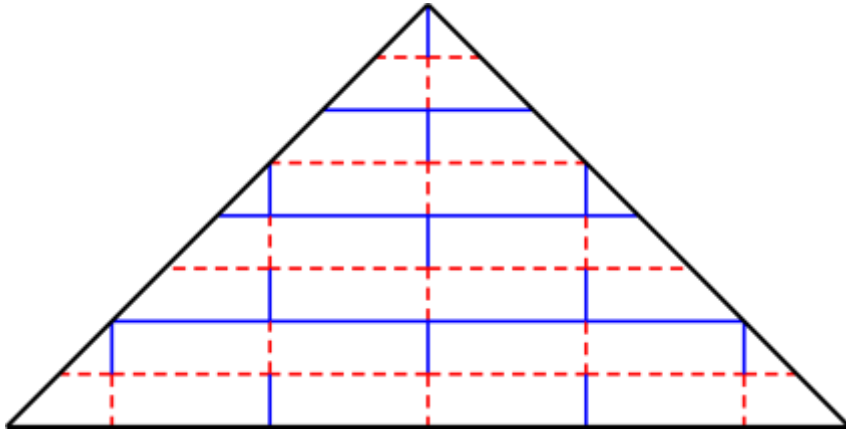


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# Sail Folding Pattern

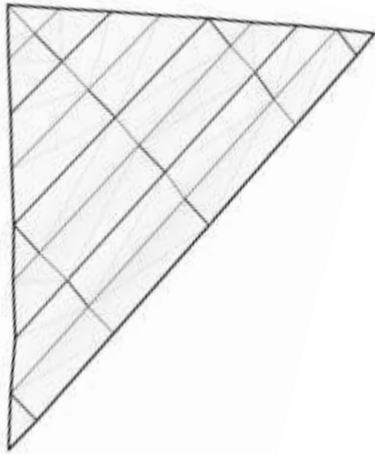


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Sail deployment deorbit system by solenoids for  
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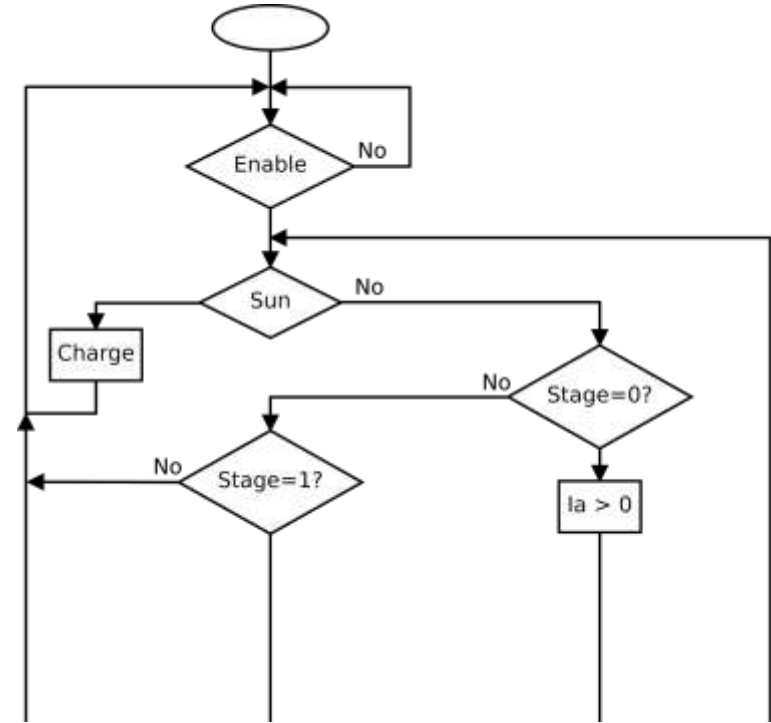
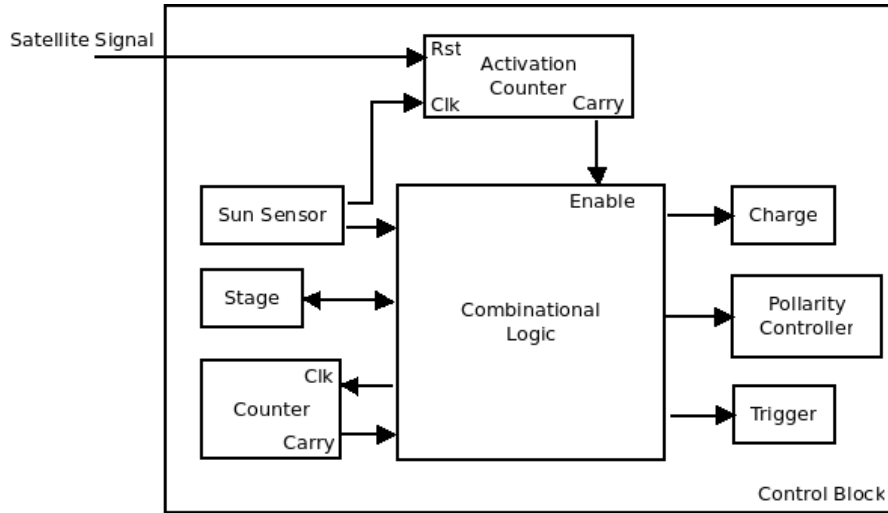
# Sail Folding Pattern



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# Control



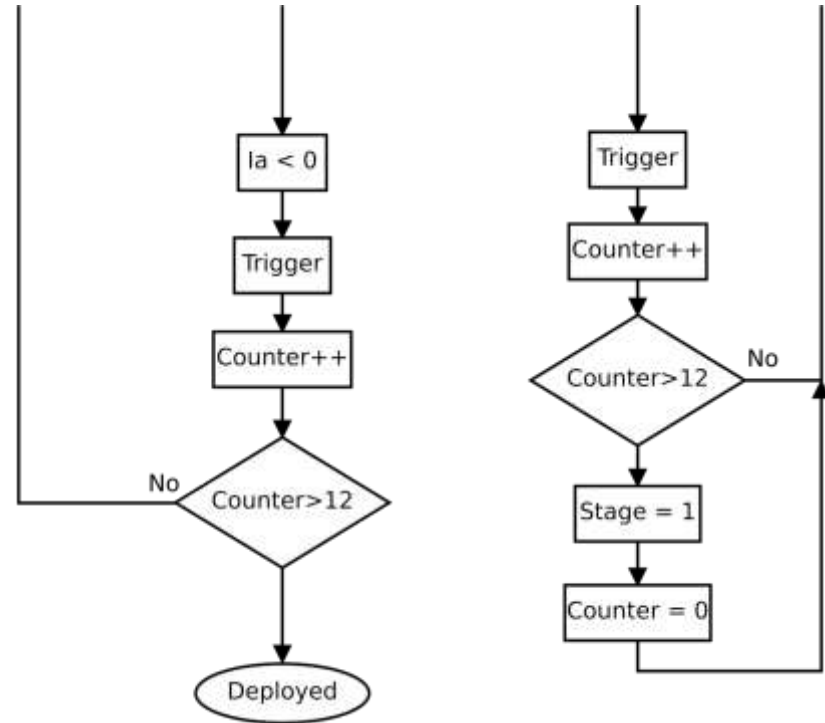
# Control

Controlling the deployment:

- Beacon type signal.
- Deactivate the deployment every 24hs.

After the satellite becomes non-cooperative:

- Beacon signal, no longer exists
- Activate the deploy, after 24hs





# Conclusions

- Linear motors works well in the experiments.
- We still work to define materials

Future work:

- Microgravity tests
- Temperature stress test and redo the shape of the housing



# Thanks to



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